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**A Research Roadmap for Substantially Improving Safety for Transit Buses through  
Autonomous Braking Assistance for Operators**

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## **ABSTRACT**

This paper documents significant negative trends and impacts on the transit industry due to bus collisions, and the resulting injuries, fatalities and casualty and liability expenses. We outline a research roadmap to counter the trends by applying autonomous collision avoidance technology and autonomous emergency braking to transit buses.

Bus transit is one of the safest ways to travel in the United States. Bus passengers are more than three times safer than automobile passengers when comparing the rate of fatalities per 100 million passenger miles. However, buses can be made even safer.

We propose a research assessment to determine: why casualty and liability claims are increasing, the potential for automated collision avoidance systems to reduce fatalities, injuries and claims in transit buses, and to initiate the development of functional requirements and standards to allow installation of collision avoidance and driver assist technology on new transit buses and retrofit of existing buses.

Dollars spent on casualty and liability expenses are wasted dollars, arguably spent to mitigate the effects of collisions that should not have happened. The best way to reduce those wasted dollars is to prevent collisions from happening, and that is what will be discussed in subsequent sections of this paper.

## **INTRODUCTION**

The purpose of this paper is to lay the groundwork for development of autonomous collision avoidance and autonomous emergency braking for transit buses. Although significant progress is being made in bringing autonomous collision avoidance and autonomous emergency braking to automobiles and trucks, the transit industry is being left behind. Bus transit has taken second place behind rail transit in the public perception of safety needs. Consequently it has not attracted attention from those who set research priorities and make funding decisions, in spite of data that show that bus exceeds rail in injuries and casualty and liability expenses.

We lay out a draft research roadmap for the adaptation to buses of proven technology that has been shown to reduce collisions and claims for automobiles. Our objectives are first to educate the industry on the magnitude of the problem, second, to provide a draft program that would lead to the desired outcomes, and third, to seek stakeholder involvement to refine the program and support to seek funding for it.

## **DIMENSIONING THE PROBLEM USING NATIONAL BUS SAFETY DATA**

Bus transit is one of the safest ways to travel in the United States. Bus passengers are more than three times safer than automobile passengers when comparing the rate of fatalities per 100 million passenger miles.<sup>1</sup> However, we believe buses can be made even safer.

As shown in Table 1, which uses data from the Federal Transit Administration (FTA) National Transit Database (NTD) for the reporting periods shown, buses and vanpools have been involved in 85,391 collisions, experienced 1,340 fatalities, 201,382 injuries, and created expenditures for casualty and liability expenses of \$5.7 billion. Included in these data are 56 fatalities and 16,312 injuries involving bus transit workers.

Recent events have focused attention on rail safety in the press. Consequently, it may be appropriate to examine whether there is an equitable balance in the application of resources to both bus and rail safety. Although we do not draw conclusions about the allocation of resources, we have included in Table 1 data comparing fatalities, injuries and costs of casualty

**Table 1 Collisions, Fatalities, Injuries, Casualty and Liability Expenses by Transit Mode 2002-2014**  
**Source: Federal Transit Administration (FTA) National Transit Database (NTD)**  
<http://www.ntdprogram.gov/ntdprogram/data.htm> accessed July 17, 2015

Mode	Reporting Period 2002-2014 Except as Noted					Reporting Period 2002-2013 Except as Noted		
	Collisions	Fatalities		Injuries		Total Casualty and Liability Expenses by Mode	Average Annual Vehicle Fleet	Average Annual Cost of Casualty and Liability Expenses per Vehicle
		Employees <sup>a</sup>	Total	Employees <sup>a</sup>	Total			
<b>Commuter Bus (CB)<sup>b</sup></b>	<b>94</b>	<b>0</b>	<b>3</b>	<b>33</b>	<b>390</b>	<b>\$34,599,730<sup>b</sup></b>	<b>2357</b>	<b>\$4,894</b>
<b>Demand Responsive (DR)</b>	<b>14,513</b>	<b>6</b>	<b>120</b>	<b>3,055</b>	<b>19,833</b>	<b>\$668,245,896</b>	<b>28,449</b>	<b>\$1,957</b>
<b>Demand Responsive Taxi (DT)<sup>c</sup></b>	<b>144</b>	<b>0</b>	<b>3</b>	<b>33</b>	<b>262</b>	<b>\$2,123,284<sup>c</sup></b>	<b>3,960</b>	<b>\$134</b>
<b>Motor Bus (MB)</b>	<b>69,722</b>	<b>49</b>	<b>1,185</b>	<b>13,079</b>	<b>177,931</b>	<b>\$4,908,851,572</b>	<b>62,307</b>	<b>\$6,565</b>
<b>Bus Rapid Transit (RB)<sup>b</sup></b>	<b>55</b>	<b>0</b>	<b>0</b>	<b>18</b>	<b>358</b>	<b>\$2,752,895<sup>b</sup></b>	<b>137</b>	<b>\$6,714</b>
<b>Trolley Bus (TB)</b>	<b>486</b>	<b>0</b>	<b>10</b>	<b>59</b>	<b>2,096</b>	<b>\$57,539,948</b>	<b>581</b>	<b>\$8,257</b>
<b>Van Pool (VP)</b>	<b>377</b>	<b>1</b>	<b>19</b>	<b>35</b>	<b>512</b>	<b>\$79,677,613</b>	<b>9,581</b>	<b>\$693</b>
<b>Total Bus, Demand Responsive and Van Pool</b>	<b>85,391</b>	<b>56</b>	<b>1,340</b>	<b>16,312</b>	<b>201,382</b>	<b>\$5,753,790,938</b>	<b>N/A</b>	<b>N/A</b>
<b>Total Rail<sup>d,e</sup></b>	<b>6,118</b>	<b>36</b>	<b>1,303</b>	<b>1,462</b>	<b>89,806</b>	<b>\$3,174,067,800</b>	<b>N/A</b>	<b>N/A</b>

<sup>a</sup> Includes transit operators, transit employees, and other workers

<sup>b</sup> Data reporting started in 2012, included in Motor Bus (MB) for prior years

<sup>c</sup> Data reporting started in 2011, included in Demand Responsive (DR) for prior years

<sup>d</sup> Rail includes Automated Guideway (AG), Cable Car (CC), Commuter Rail (CR), Heavy Rail (HR), Light Rail (LR), Monorail/Guideway (MG), Monorail (MO), Streetcar Rail (SR), Hybrid Rail (YR);

<sup>e</sup> Collisions, fatalities, and injuries are not reported for Commuter Rail (CR).; casualty and liability expenses are included for Commuter Rail (CR).;

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1 and liability expenses for bus modes and the total for rail transit modes. A few highlights from a  
 2 comparison between bus and rail show that injuries to transit workers are eleven times greater for  
 3 bus than rail, and passenger injuries for bus are more than twice the number of rail injuries.  
 4 Even more compelling is the fact that casualty and liability expenses for bus at \$5.7 billion are  
 5 more than 80 per cent higher than for rail.

### 7 **Casualty and Liability Expenses**

8 Casualty and liability expenses are reported on an annual basis to the FTA NTD as part of the  
 9 Operating Expense report.<sup>2</sup> According to the manual, casualty and liability expenses “are the  
 10 expenses a transit agency incurs for loss protection. If a transit agency is liable for someone’s  
 11 loss, then the agency must report all applicable compensation under this object class. Casualty  
 12 and liability costs include: physical damage insurance premiums, recovery of physical damage  
 13 losses for public liability and property damage insurance premiums, insured and uninsured  
 14 public liability and property damage settlement pay outs and recoveries, and other corporate  
 15 insurance premiums (e.g., fidelity bonds, business records insurance)”<sup>3</sup> Expenses are broken out  
 16 by mode code for each agency and categorized as either: general administration, vehicle  
 17 maintenance, or non-vehicle maintenance. Not all expenses attributable to vehicle collisions are  
 18 reported as casualty and liability expenses. Such costs may include the following:

- 19 • Accident investigation
- 20 • Drug and alcohol testing
- 21 • Emergency services response
- 22 • Hearings and discipline
- 23 • In-house legal services
- 24 • In-house vehicle repair
- 25 • Lost fare revenue
- 26 • Overtime wages
- 27 • Passenger and service delays
- 28 • Sick time
- 29 • Spare vehicles and replacements
- 30 • Vehicle recovery
- 31 • Workers compensation

32 Transit agencies are required to submit reports on individual incidents and collisions for  
 33 the Safety and Security Module of the NTD. Although property damage expenses exceeding  
 34 certain thresholds are reported for each incident, the costs of individual casualty and liability  
 35 claims for injuries and fatalities are not reported by incident. Consequently, it is difficult to  
 36 assemble the total cost to an agency of an individual collision.

37 Safety reporting typically uses the numbers and rates of injuries and fatalities as metrics.  
 38 Although as humans we are emotionally moved when people are injured or killed in an accident,  
 39 if they are unknown to us and unseen by us, the numbers are abstract and the significance of  
 40 changes is difficult to comprehend. However, the total casualty and liability expense of claims  
 41 can be considered as an index of the misery caused by collisions, and is easily tracked over time.

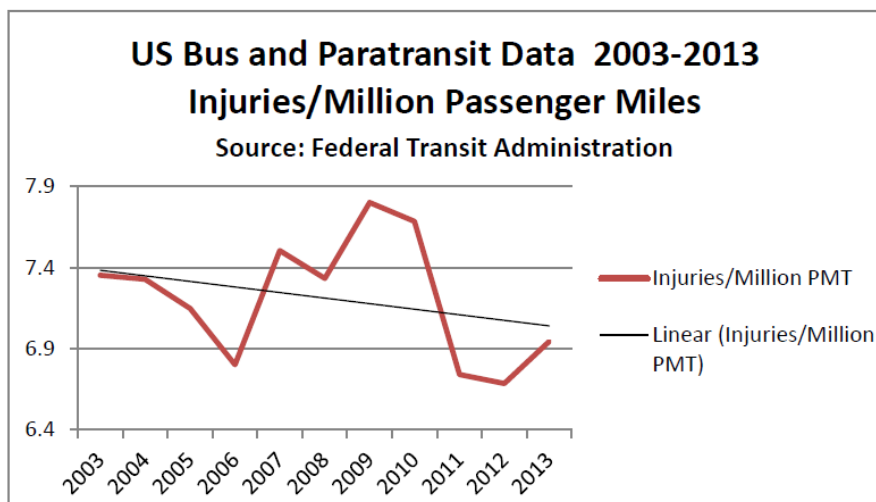
42 Many transit agencies are self-insured for claims up to a specified monetary threshold  
 43 and purchase insurance to cover extraordinary losses. In several states, transit agencies have  
 44 organized transit insurance pools, which handle claims and combine the purchasing power of a  
 45 number of properties to receive better rates from insurance providers.

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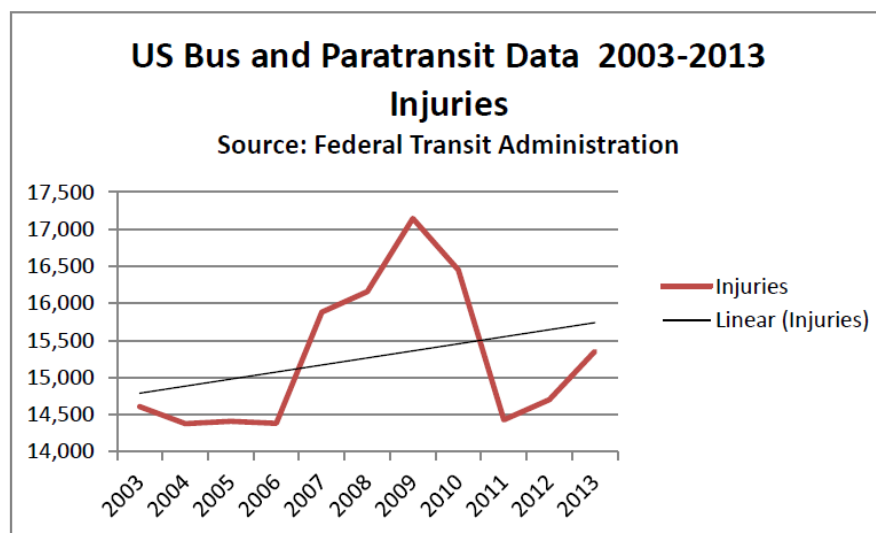
1 Dollars spent on casualty and liability expenses are wasted dollars, arguably spent to  
 2 mitigate the effects of collisions that should not have happened. The best way to reduce those  
 3 wasted dollars is to prevent collisions from happening, and that is what will be discussed in  
 4 subsequent sections of this paper.

### 6 Trends in Bus Injuries and Casualty and Liability Expenses

7 Figure 1 shows that the rate of injuries per million passenger miles fluctuates over the period  
 8 2003 to 2013, but the trend is generally downward, which is good. Figure 2, however, shows  
 9 that the number of injuries per has been trending upward. Figure 3 shows sharp fluctuations in  
 10 casualty and liability expenses with a significant upward trend over the period. The research  
 11 roadmap will include an examination of these trends and underlying factors that drive them.  
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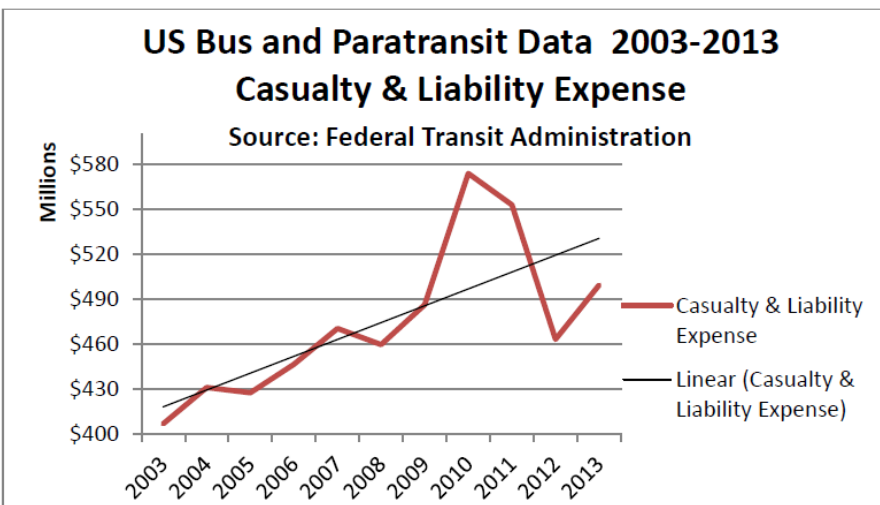


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 14  
 15 **Figure 1 US Bus and Paratransit Injuries per Million Passenger Miles**  
 16



17  
 18 **Figure 2 US Bus and Paratransit Injuries per Year**

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3

4 **Figure 3 US Bus and Paratransit Casualty and Liability Expenses**

5

6 **AN ANALYSIS OF BUS COLLISION CLAIMS**

7 Three major transit insurance organizations, the California Transit Indemnity Pool, the Ohio  
8 Transit Risk Pool, and the Washington State Transit Insurance Pool, together with King County  
9 Metro Transit, collaborated on an analysis of bus claims to determine the potential for claims  
10 reduction through application of autonomous collision avoidance and autonomous emergency  
11 braking.<sup>4</sup> The analysis was based on claims resolved during the period 2004 to 2014. Of the  
12 total \$191 million in gross incurred losses, \$113 million were for claims less than \$100 thousand  
13 and \$78 million were for claims greater than \$100 thousand. The analysis focused on claims  
14 greater than \$100 thousand.

15 The majority of losses, 74 percent, were collision-related. Collisions with pedestrians,  
16 bicyclists, and motorcyclists accounted for 46 per cent. Forward collisions with vehicles  
17 accounted for another 15 percent. Ten percent of the collision losses were considered “non-  
18 preventable” by forward warning systems, and three percent were categorized as “other.” Based  
19 on the transit risk pool analysis, forward collision avoidance systems with autonomous  
20 emergency braking have the potential to prevent 61 percent of claims greater than \$100  
21 thousand. An analysis of the top five large claims, ranging from \$3.3 million to \$5 million,  
22 showed that four of the five could have been prevented by autonomous collision avoidance  
23 technology, for a savings of \$18 million.

24

25 **COLLISION AVOIDANCE TECHNOLOGY**

26 In 2004, 2007, and 2013 the Federal Transit Administration released research reports on the  
27 potential for technology to reduce bus crashes.<sup>5,6,7</sup> These reports concluded that the systems  
28 envisioned at the time, which would warn bus drivers of impending collisions, could be effective  
29 in reducing costs.

30

31 Several vendors are offering collision avoidance warning systems for buses. Roscoe  
32 Vision Systems and Mobileye are offering a camera-based pedestrian detection system for buses  
33 that recognizes when a bus is at risk of colliding with a pedestrian and provides both audible and  
visual warnings to the operator.<sup>8</sup> CycleEye is testing a system that uses cameras and radar to

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1 detect cyclists in blind spots close to a bus.<sup>9</sup> Other vendors including Clever Devices and  
2 Protran Technology offer systems that broadcast audible warnings to pedestrians that a bus is  
3 turning.<sup>10,11</sup>

4 Although intended for trucks rather than buses, Soterea, Inc. has teamed with Klam  
5 America, Inc. to develop a promising radar-based system, “Autonobox” which detects vehicles,  
6 pedestrians and obstacles in the path of a truck and activates an electromagnetic driveshaft  
7 retarder to slow and stop the vehicle prior to a collision.<sup>12,13</sup>

### 9 **The Need for Autonomous Driver Assistance**

10 Although driver warnings may be effective, in the time it takes to respond to an imminent  
11 collision, a bus typically can travel as much as six times its own length before the brakes are  
12 applied. Chang and Chang presented an experimental study in which bus driver perception-  
13 reaction times were measured.<sup>14</sup> They found that the average perception-reaction times for the  
14 various trials ranged from 1.6 to 2.32 seconds with a standard deviation of 0.54 to 0.88 seconds.  
15 Autonomous braking and maneuvering could reduce that delay significantly, reducing the  
16 potential for collisions and injuries, and saving lives.

17 Automobiles are now entering the market with automated systems that not only sense that  
18 a collision is imminent, but actually take control of throttle, steering and braking functions to  
19 avoid or mitigate collisions. In particular, systems for autos are available that will initiate  
20 autonomous braking to bring a vehicle to a stop prior to collision with a pedestrian or vehicle,  
21 even if the vehicle operator does not apply the brakes manually.<sup>15</sup> The Insurance Institute for  
22 Highway Safety (IIHS) has concluded that forward collision avoidance technologies have  
23 reduced claims. According to IIHS, Volvo XC60 SUV’s equipped with autonomous braking  
24 experienced 33 percent fewer bodily injury claims, 15 percent fewer property damage claims,  
25 and 20 percent fewer collision claims.<sup>16</sup>

26 The National Transportation Safety Board (NTSB) has called for immediate action to  
27 require these systems on new vehicles. The NTSB reported that forward collisions were reduced  
28 by 71 percent for trucks equipped with collision avoidance systems (CAS) that included  
29 autonomous emergency braking (AEB) and electronic stability control (ESC). That test spanned  
30 30 months and included 12,600 truck-tractors.<sup>17</sup>

### 32 **The Need for Standards and Specifications**

33 Because transit buses typically can stay in service for 12 to 18 years and often carry  
34 standees, their technology requirements will differ from those for trucks and autos. Emergency  
35 braking rates for transit buses must consider that standing passengers may be thrown off balance  
36 if the jerk and deceleration rates are too high. Abernethy, et al, reported only two known human  
37 studies of effects of deceleration on public transit passengers.<sup>18</sup> One of the studies cited was  
38 conducted in 1932 and measured the deceleration forces that would cause standing passengers to  
39 lose balance.<sup>19</sup>

40 Buses and vans purchased with FTA funds are expected to remain in service for at least  
41 12 years.<sup>20</sup> Digital technology often becomes obsolete in a matter of months. Autonomous  
42 collision avoidance systems should not be expected to last for the life of the bus. Software and  
43 electronic components in the systems will be replaced by newer versions over time as the  
44 original versions will no longer be available. Sensors and processors are subjected to harsh  
45 environmental conditions in the transit operating environment. It is expected that components  
46 and even entire systems will need to be replaced over the life of the vehicle.

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1           When system maintenance or replacement is required, vehicles must be taken out of  
2 service and spend time in a maintenance facility. Fleet availability and the impact on  
3 maintenance resources will be a concern. For those reasons, component change outs need to be  
4 done quickly and multiple sources will be needed to insure that replacement component prices  
5 are competitive.

6           With slightly over 60,000 vehicles, the transit bus industry in the United States is a niche  
7 market compared with automobiles and trucks. Bus manufacturers have told us that they act as  
8 systems integrators for new technology by purchasing and installing systems that are specified  
9 by their transit agency customers. As a result there is little financial incentive for bus  
10 manufacturers to undertake development of these systems. Consequently, the push for  
11 innovation and standards in this area must come from transit agencies and those government  
12 bodies charged with oversight of transit safety.

13           Purchasing buses for a transit authority is not a simple task. Buses are usually purchased  
14 under a competitive procurement process in which an agency issues a request for proposals to  
15 bus manufacturers that specifies what the agency wishes to buy. Bus manufacturers then submit  
16 proposals that contain technical information on the buses they propose to supply along with the  
17 prices for the buses and optional features. The agencies will evaluate each proposal and  
18 generally award a contract to the manufacturer that meets the agency's technical requirements  
19 and offers the lowest price.

20           Integral to the process is the need for the agency to develop a detailed specification for  
21 the features it wants on the buses. Specifications range from the color scheme, to the type of  
22 engine and fuel, to small details like the location of drain plugs. The American Public  
23 Transportation Association (APTA) has developed guidelines for bus procurement that agencies  
24 can use in their requests for proposals.<sup>21</sup> The APTA outline runs 284 pages long and includes  
25 more than 300 alternatives for technical requirements from which an agency can choose.

26           The APTA guidelines contain extensive technical detail, but they do not include  
27 information on, or specifications for, collision avoidance systems and autonomous emergency  
28 braking. Although other standards bodies are beginning to work on standards for autos and  
29 trucks, standards for buses will need to address unique bus characteristics such as the following:

- 30           • Blind spot locations
- 31           • Component replacement and maintenance requirements
- 32           • Forces acting on seated and standing passengers
- 33           • Operator training and workload
- 34           • Proximity of pedestrians and waiting passengers
- 35           • Sensor placement
- 36           • Vehicle lifespan

## 37 38 **RESEARCH AND DEVELOPMENT ROADMAP**

39           The draft research roadmap presented here includes a statement of the research objectives as  
40 questions to be answered, and four separate research phases. The phases are generally sequenced  
41 in chronological order, but may overlap. Once this general outline has been reviewed by  
42 stakeholders, it is expected that changes will be incorporated and each phase will be divided into  
43 tasks, with a schedule and budget.

### 44 45 **Research Objectives and Outcomes**

- 46           • Why have casualty and liability expenses trended upward?



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- 1 • How can the industry more accurately account for the total costs of bus collisions?
- 2 • What is the correlation between costs and type of collision?
- 3 • What types of autonomous collision avoidance technologies have the greatest potential to
- 4 reduce casualty and liability expenses?
- 5 • What requirements and standards are needed to allow transit operators to specify
- 6 autonomous collision avoidance technology for new bus procurements and retrofits?
- 7 • Given that buses may remain in service for 15 to 18 years, and digital technology can
- 8 become obsolete within 18 months to two years, how should buses be configured to allow
- 9 rapid and cost-effective replacement of components and retrofit with updated
- 10 technology?
- 11 • What is the process for testing and certifying autonomous collision avoidance systems?

## 12 **Phase 1**

- 13 • Create a broad, inclusive stakeholder group of transit agencies and other members of the
- 14 transit industry, and achieve a comprehensive view of the problem and potential solutions
- 15 from all sides.

16 Phase 1 will establish an effective project management structure and create an industry-wide  
 17 stakeholder group including representatives of transit agencies, risk management and insurance  
 18 providers, consultants, vehicle manufacturers, systems developers, standards organizations,  
 19 vendors, motor vehicle regulators, and USDOT officials. Volunteers from the stakeholder group  
 20 will be asked to participate in expert technical working groups to assist in the development and  
 21 balloting of consensus standards for autonomous collision avoidance technology for transit  
 22 buses. These standards will make it possible to install life-saving advanced technology on new  
 23 transit buses and to retrofit exiting buses.

24 **Expert Technical Working Groups (ETWG's)** – ETWG's are working groups charged with  
 25 the development of functional requirements and standards through a consensus process and  
 26 balloting. Each ETWG will be chaired by a subject matter expert who will develop an initial  
 27 white paper to articulate specific technical issues that need to be addressed in the standards  
 28 development process. ETWG membership will be publicly and broadly solicited throughout the  
 29 transit industry. Announcements will be sent to interested parties and the creation of the working  
 30 groups will be advertised in APTA publications to recruit volunteers. ETWG members will  
 31 include volunteers representing stakeholder groups such as transit agency staff, risk management  
 32 and insurance providers, consultants, vehicle manufacturers, systems developers, standards  
 33 organizations, and vendors. The project includes the following ETWG's:

- 34 • Claims analysis and data collection
- 35 • Human factors/operations/safety
- 36 • Bus interfaces/systems/maintainability
- 37 • Autonomous systems and controls
- 38 • Testing and certification

39  
 40

1 **Phase 2**

2

- 3 • Conduct a research assessment of why casualty and liability claims are increasing and  
4 determine the potential for automated collision avoidance systems to reduce fatalities,  
5 injuries and claims.

6 Phase 2 will provide transit agencies with an accurate and comprehensive understanding of the  
7 total costs of bus collisions, the reasons that the costs of collisions are increasing, and the  
8 relationship between costs and types of accidents. Using the National Transit Database (NTD),  
9 we will provide a detailed examination of the historical trends of steadily rising casualty and  
10 liability expenses and provide insights through statistical analysis of factors that are shown to be  
11 correlated with the increases in costs. In addition to NTD data, participating transit agencies and  
12 insurers will provide detailed data that will allow the researchers to link individual claims and  
13 other expenses with individual incidents to assemble an accurate record of the total agency cost  
14 of each collision. Although this data will be used in the project to identify cost-effective  
15 autonomous collision avoidance technologies, it is expected that transit agency safety and risk  
16 managers immediately will be able to increase bus operator awareness of high risk situations and  
17 improve their ability to reduce the frequency and severity of collisions.

18 **Phase 3**

- 19 • Develop functional requirements and standards to allow installation of collision  
20 avoidance and driver assist technology on new transit buses and retrofit of existing buses.

21 Phase 3 of the project will use expert technical working groups created in Phase 1 to develop  
22 functional requirements, specifications and standards that will: 1) define the capabilities and  
23 performance requirements for autonomous collision avoidance technology for buses, and 2)  
24 allow collision autonomous collision avoidance technologies to be retrofitted to buses, using  
25 competitive procurements and “plug and play” interfaces. The major deliverables of this task  
26 will be a balloted set of standards for autonomous collision avoidance technology and for the  
27 electromechanical on-board interfaces needed to host the technology.

28 **Phase 4**

- 29 • Develop a prototype test bed that would allow developers of innovative collision  
30 avoidance and driver assist technologies to work with transit agencies and researchers to  
31 expedite development and deployment.

32 Phase 4 involves development and testing of the following elements: 1) an on-board test-bed  
33 network using electromechanical interface standards developed in Phase 3, that will  
34 accommodate the installation and testing of prototype autonomous collision avoidance  
35 technologies, 2) a collision avoidance system simulator that can be installed to test the bus’s  
36 ability to host, and autonomously respond to inputs from, a collision avoidance system, and 3) a  
37 data logger and analyzer to monitor multiple performance parameters of both the bus and the  
38 autonomous collision avoidance technology and produce reports that can be used to certify

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1 compliance with the performance requirements and standards. Phase 4 will include an extensive  
2 field operational test of all three elements.

### 3 **Research Products**

4 This program would develop the following products: 1) a review and analysis of the  
5 comprehensive costs to transit agencies of various types of bus collisions, 2) functional  
6 requirements and performance specifications for autonomous collision avoidance technology for  
7 buses, 3) standards for interfaces between buses and autonomous collision avoidance technology,  
8 4) an on-board test-bed network using the performance and interface standards, that will  
9 accommodate the installation and testing of prototype autonomous collision avoidance  
10 technologies, 5) a collision avoidance system simulator that can be installed on a new or  
11 retrofitted bus to test the bus's ability to host, and autonomously respond to inputs from, a  
12 collision avoidance system, and 6) a data logger/analyzer that will monitor multiple performance  
13 parameters of both the bus and the autonomous collision avoidance technology and produce  
14 reports that can be used to certify compliance with the performance requirements and standards.  
15

### 16 **CONCLUSION**

17 This paper documents a serious problem for the transit bus industry, rising numbers of injuries  
18 and a sharp increase in casualty and liability expenses for buses. We show that bus lags behind  
19 rail transit in these key safety metrics. The paper presents a work program for the development  
20 of functional standards and certification procedures for autonomous bus collision avoidance  
21 systems and autonomous emergency braking that draws on a partnership among various  
22 stakeholders including the American Public Transportation Association (APTA), Princeton  
23 University Autonomous Vehicle Engineering (PAVE), and the Washington State Transit  
24 Insurance Pool (WSTIP).

25 The missing piece is how to communicate the message to transportation decision-makers  
26 that a relatively small investment in research and development could yield major savings in lives,  
27 injuries and dollars. Current policies at the federal level have focused discretionary spending on  
28 programs that emphasize job creation rather than research. However, data show that the research  
29 and development of autonomous collision avoidance and autonomous emergency braking for  
30 buses have the potential to reduce annual casualty and liability expenses and allow scarce transit  
31 funds to be reallocated in ways that would not only create jobs, but would save lives and reduce  
32 injuries, as well. This paper is a starting point for the educational process of communicating the  
33 value of this research and building a coalition to seek funding and get it done.  
34

### 35 **REFERENCES**

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